

(12) UK Patent Application (19) GB (11) 2 363 173 A

(43) Date of A Publication 12.12.2001

(21) Application No 0013727.3

(22) Date of Filing 07.06.2000

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(51) INT CL⁷
F16H 3/72

(52) UK CL (Edition S)
F2D DEC DE1 DE3 DE46 DE50 DE72 DE78 DE83 DE86

(56) Documents Cited
US 5730676 A US 5603671 A US 5577973 A
US 5558589 A

(58) Field of Search
UK CL (Edition S) F2D DEC
INT CL⁷ F16H 3/72
ONLINE: WPI; EPODOC; JAPIO.

(54) Abstract Title

Epicyclic transmission with electric motors to vary output speed

(57) An epicyclic transmission comprises a first annulus gear 26 grounded by a switched reluctance type first electric motor 13 and a second sun gear 18 grounded by a second motor 15 of the switched reluctance type. The transmission has control means which permits the speed of the motors 13, 15 to be varied so as to alter an output speed of the transmission. First annulus gear 26 is engaged with first planet wheels 24 having a first carrier that is connected to a second annulus gear 30. Second annulus gear 39 drives second planet wheels 31 having a second carrier which may be connected to an output shaft 37. The first carrier and first planet wheels 24 may be driven, via flywheel 22, by an input to the transmission. First planet wheels 24 also drive a first sun gear 19 which is coupled to the second sun gear 18.

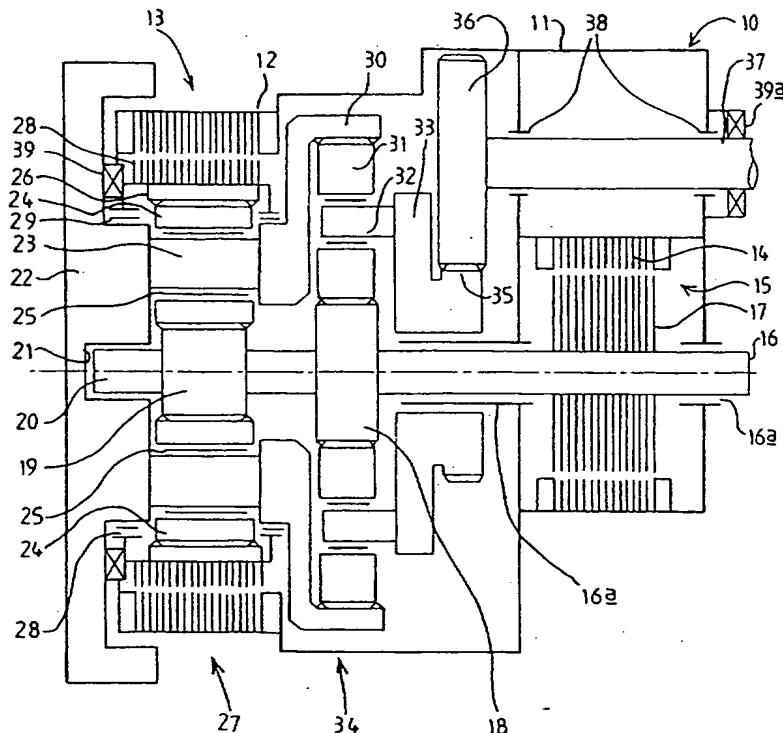


FIG 1

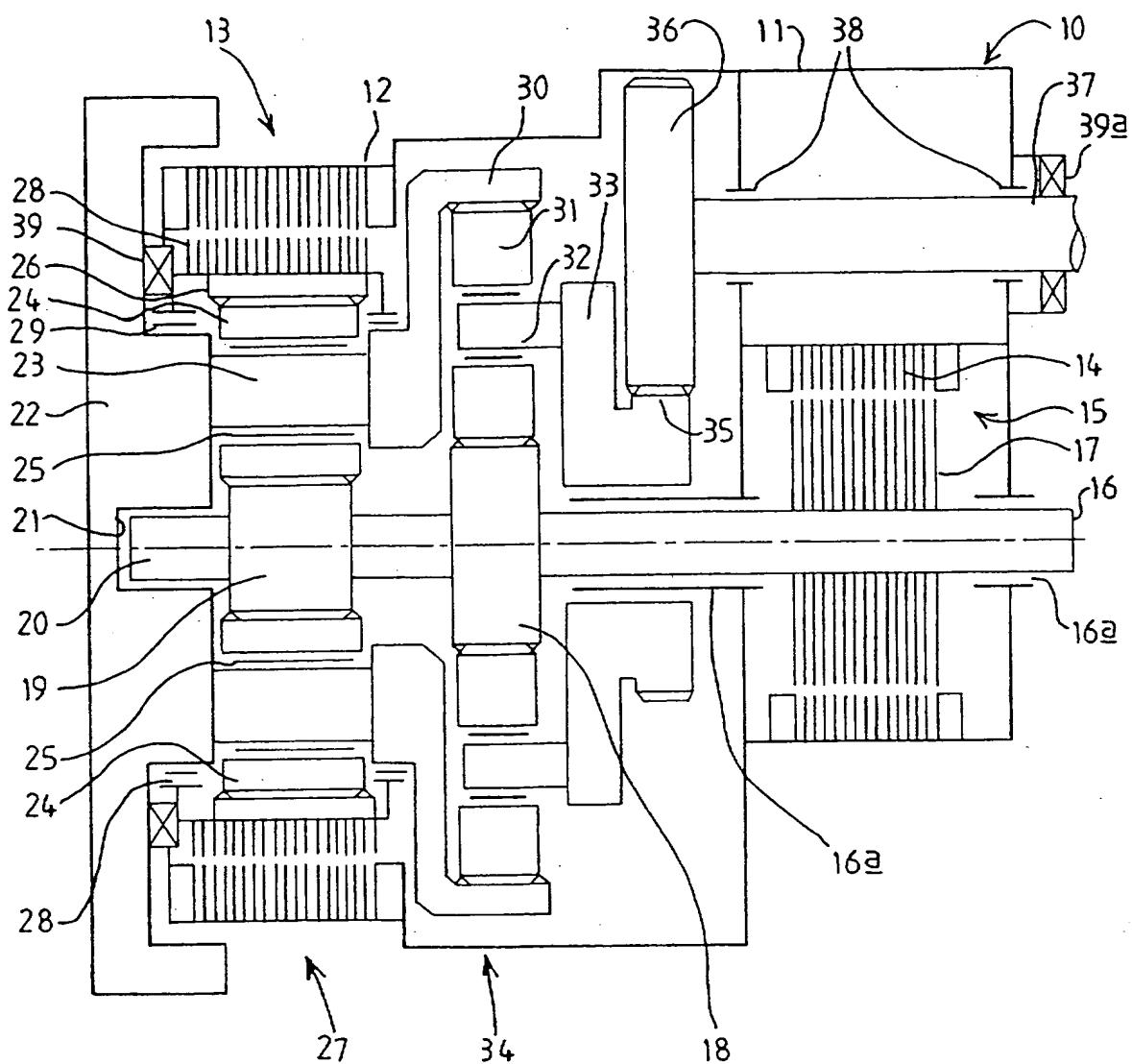


FIG 1

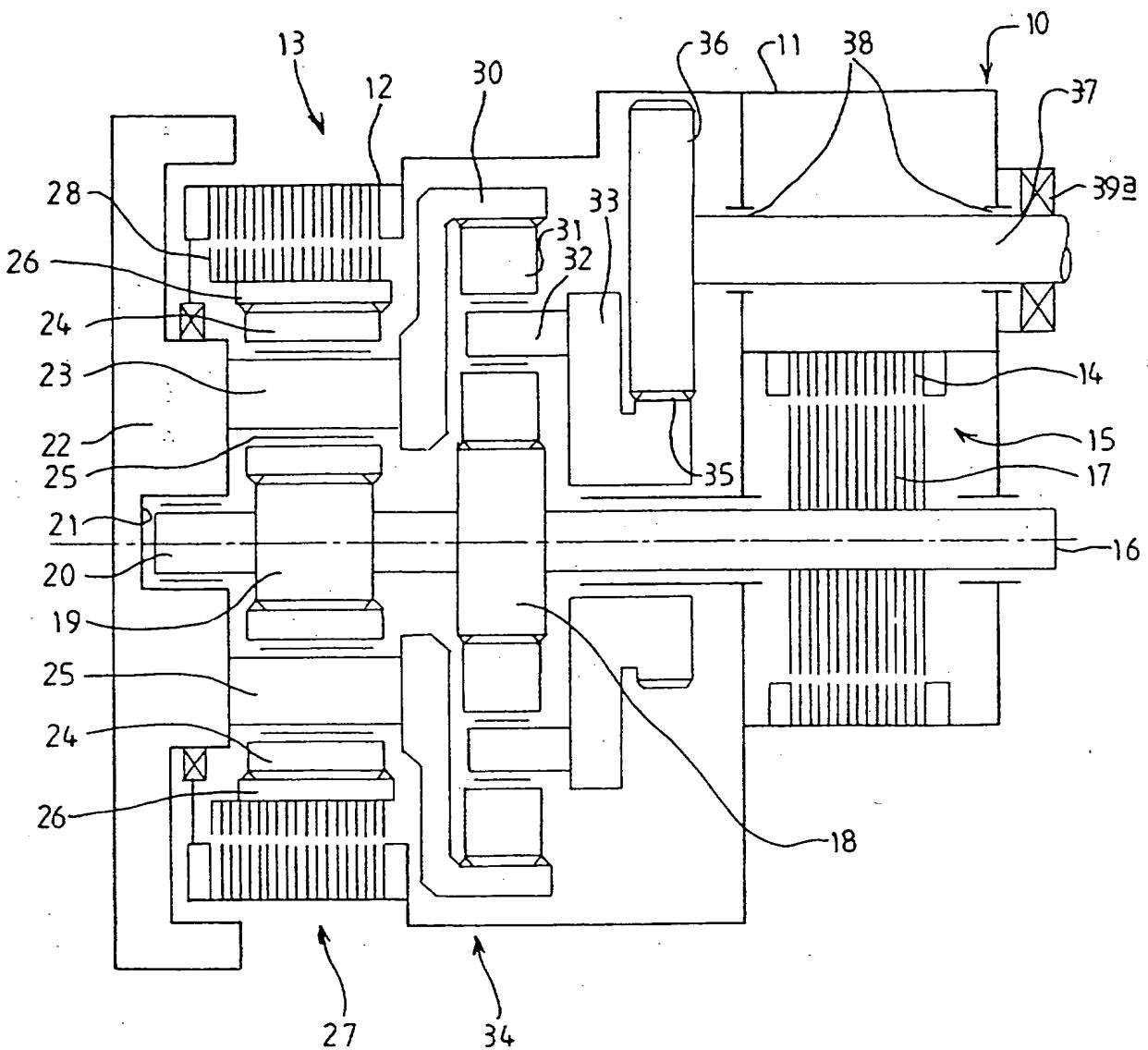


FIG 2

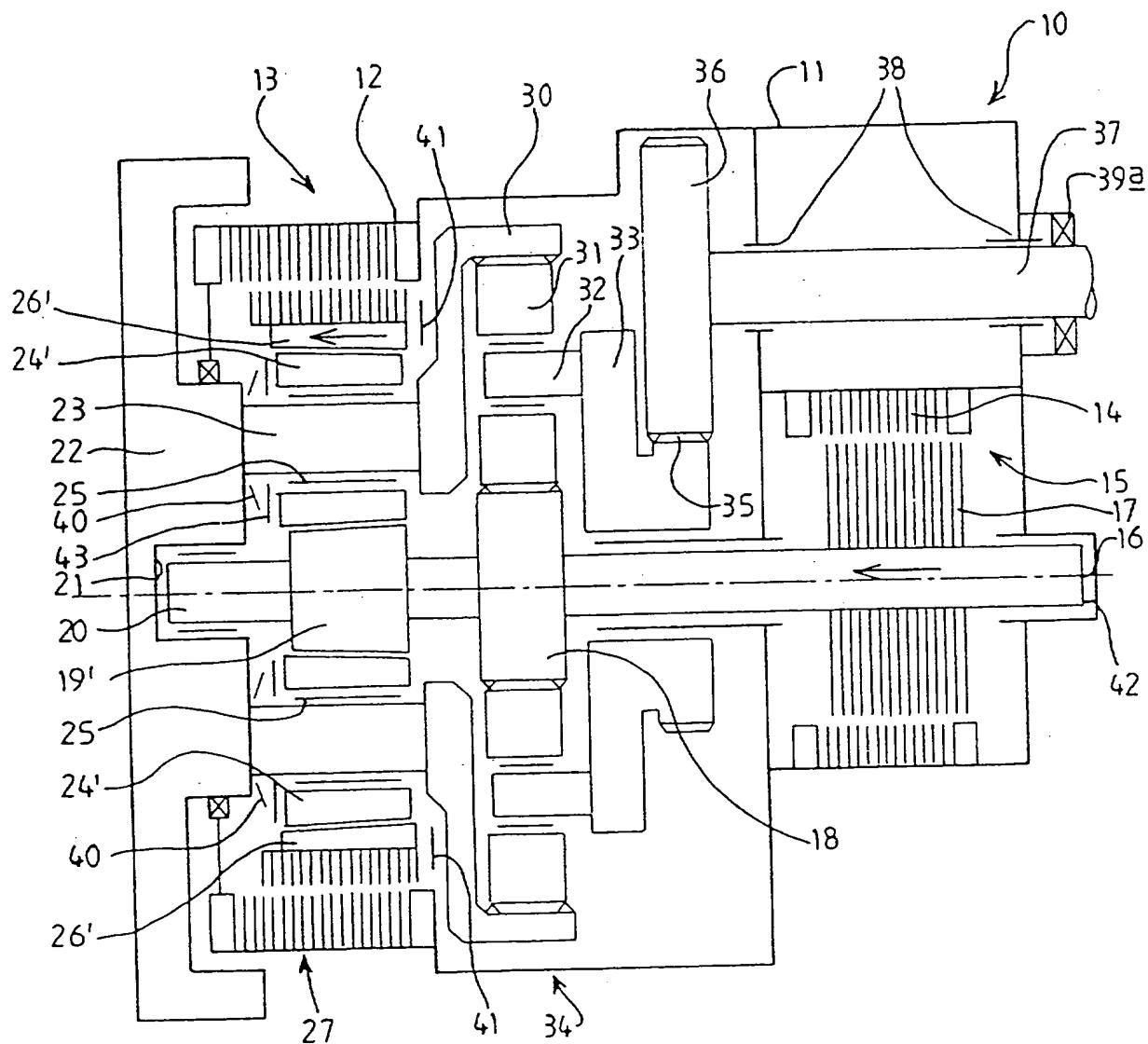


FIG 3

Spread Sheet Model, 74 kW engine at 3200 RPM input					
	Ro -3.62	EP1 0	4.62	E1	Ro pos 0
Pos	output	engine	ring		Ro pos 0
	sun speed	carr.speed	ring		sun speed
RPM	-710	3200	4280	4280	RPM
	sun torque	carr.torque	ring		sun torque
Nm	5	-25	20	19.9	Nm
	sun power	carr. power	ring		sun power
kW	-0.4	-8.5	8.9	8.9	kW
	E1	Input EP1	E2		E1

slider value
only
7280
ring speed
RPM slide
E1



EP1/2 = epicyclic stages
E1/2 = electric motors

Full power, min output speed setting
max torque on E2 motor = 120 Nm
electric power flow 8.9 kW
no electric power flow from external source

Mechanical and electrical losses are not calculated in this spreadsheet

Fig 4 Sheet 1

Electric Power Split Transmission Spread Sheet Model, 74 kW engine at 3200 RPM input						EP1	EP2	E2
	Ro	Pos	Ro	Pos	Ro	0	2.15	3.15
Ro	-3.62	EP1	3.62	4.62	E1			
Pos	0	output	3.62	ring				
		engine						
sun speed	carr.speed				sun speed	carr.speed	ring	engine
RPM	16008	3200	-338	-338	RPM	16008	7266	3200
Nm	-33	154	-121	-121	Nm	sun torque	carr.torque	ring
kW	-56.0	51.8	4.3	4.3	kW	sun power	carr. power	ring
	E1	Input EP1	E2		E1	51.8	-74.0	22.2
							-4.3	-4.3
							0.0	0.0
								74

slider value

only 2662

ring speed

RPM slide E1

EP1/2 = epicyclic stages
E1/2 = electric motors

Full power, max output speed setting
max electric motor speed = 16000 RPM
electric power flow 4.3 kW
no electric power flow from external source

Mechanical and electrical losses are not calculated in this spreadsheet

Fig 4 Sheet 2

Electric Power Split Transmission Spread Sheet Model, 74 kW engine at 3200 RPM input							
	Ro	-3.62	EP1		Ro	-2.15	EP2
Pos	0	3.62	4.62	E1	Pos	0	2.15
output engine					sun speed	carr.speed	ring
sun speed	carr.speed	ring	4085	RPM	-4	2183	3200
RPM	-4	3200	4085	RPM	sun torque	carr.torque	-4
sun torque	carr.torque	ring	0	Nm	103	-324	3200
Nm	0	0	0	Nm	sun power	carr. power	221
sun power	carr. power	ring	0.1	kW	0.0	-74.0	221
kW	0.0	0.0	0.0	kW	0.0	74.0	net el.
	E1	Input EP1	E2		E1	Output EP2 part engine	0.0

slider value
only
7085
ring speed
RPM slide
E1

EP1/2 = epicyclic stages
E1/2 = electric motors

Full power, first node point setting

no internal electric power flow
no electric power flow from external source

Mechanical and electrical losses are not calculated in this spreadsheet

Fig 4 Sheet 3

Electric Power Split Transmission Spread Sheet Model, 74 kW engine at 3200 RPM Input				EP1				EP2			
Ro	Pos	EP1	E1	Ro	Pos	-2.15	EP2	Ro	Pos	-2.15	E2
0	0	3.62	4.62			0	2.15			3.15	
output	engine					sun speed	output	ring			engine
sun speed	carr.speed	ring				carr.speed	car.ring	ring			
RPM	14788	.3200	-1	RPM	14788	6879	3200	14788			3200
Nm	-33	151	-118	Nm	33	-103	70	0.0			221
sun power	carr. power	ring		sun power	carr. power	ring	ring				
kW	-50.5	50.5	0.0	kW	50.5	-74.0	23.5	0.0	net el.	0.0	74
	E1	Input EP1	E2			E1	Output EP2 part engine				

◀ ▶

slider value
only
2999

ring speed
RPM slide
E1

EP1/2 = epicyclic stages
E1/2 = electric motors

Full power, second node point setting

no internal electric power flow
no electric power flow from external source

Mechanical and electrical losses are not calculated in this spreadsheet

Fig 4 Sheet 4

Electric Power Split Transmission Spread Sheet Model, 74 kW engine at 3200 RPM input					
	Ro	EP1	EP2	Ro	EP2
Pos	-3.62	0	-2.15	0	2.15
output	3.62	4.62	E1	ring	ring
sun speed	engine	carr.speed	ring	sun speed	ring
RPM	5347	3200	2607	RPM	5347
sun torque	carr.torque	ring	ring	sun torque	carr.torque
Nm	-21	97	-76	-75.7	Nm
sun power	carr. power	ring	ring	sun power	carr. power
kW	-11.7	32.4	-20.7	-20.7	kW
E1	Input EP1	E2	E1	Output EP2	part engine

slider value
only
5607
ring speed
RPM slide
E1

EP1/2 = epicyclic stages
E1/2 = electric motors

Full power, max electric power between node points
(can be avoided by engine speed variation)
electric power flow = 20.7 kW
no electric power flow from external source

Mechanical and electrical losses are not calculated in this spreadsheet

Fig 4 Sheet 5

Electric Power Split Transmission Spread Sheet Model, vehicle reversing, 4 kW engine input at 1000 RPM						
	Ro	EP1		Ro	-2.15	EP2
Pos	-3.62	0	4.62	Pos	0	2.15
output	3.62	engine	E1	sun speed	carr.speed	ring
sun speed	0	engine	ring	RPM	sun speed	carr.speed
RPM	-5364	1000	2758	2758	-5364	-1020
sun torque	-14	64	ring	sun torque	carr.torque	ring
Nm	-14	64	-50	-50.0	Nm	-12
sun power	7.8	6.7	ring	sun power	carr. power	ring
kW	7.8	6.7	-14.4	kW	6.7	-4.0
				E1	E1	Output EP2 part engine
						14.4 0.0 4

slider value
only
5758
ring speed
RPM slide
E1

EP1/2 = epicyclic stages
E1/2 = electric motors

Reverse speed setting at 1000 engine RPM

electric power flow = 14.4 kW
no electric power flow from external source

Mechanical and electrical losses are not calculated in this spreadsheet

Fig 4 Sheet 6

Electric Power Split Transmission Spread Sheet Model, vehicle stopped, engine speed input at 1200 RPM					
				Ro	EP2
Ro	-3.62	EP1	4.62	-2.15	3.15
Pos	0	3.62	4.62	0	2.15
output	engine	engine	E1	output	
sun speed	carr.speed	ring		sun speed	carr.speed
RPM	-2587	1200	2246	RPM	-2587
sun torque	carr.torque	ring		sun torque	carr.torque
Nm	0	0	0.0	Nm	0
sun power	carr. power	ring		sun power	carr. power
kW	0.0	0.0	0.0	kW	0.0
		Input EP1	E2	E1	Output EP2 part engine

◀ ▶

solid r value
only
5246
ring speed
RPM slide
E1

EP1/2 = epicyclic stages
E1/2 = electric motors

Zero vehicle speed setting, held by speed control of motors
1200 RPM engine speed
no power flow, if no losses are assumed
no electric power flow from external source

Mechanical and electrical losses are not calculated in this spreadsheet

Fig 4 Sheet 7

Electric Power Split Transmission

Spr ad Sheet Model, vehicle stopped, starting engine

					Ro		-2.15	EP2	
					Pos		0	2.15	3.15
								E2	
Ro	-3.62	EP1							
Pos	0	3.62	4.62	E1					
	output	engine							
	sun speed	carr.speed	ring						
RPM	-652	300	563		RPM	sun speed	carr.speed	ring	
	sun torque	carr.torque	ring			-652	-2	300	
Nm	14	-64	50			sun torque	carr.torque	ring	
	sun power	carr. power	ring			0	0	0	
kW	-0.9	-2.0	2.9			sun power	carr. power	ring	
	E1		Input EP1	E2		0.0	0.0	0.0	

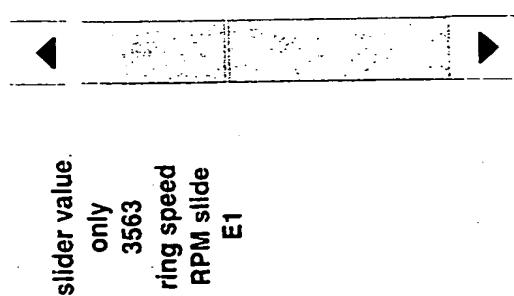


Fig 4 Sheet.8

Electric Power Split Transmission Spread Sheet Model, 74 kW engine at 3200 RPM + 10 kW electric from external source					
	Ro	Pos	Ro	Pos	
	-3.62	EP1	-2.15	EP2	3.15
Ro	-3.62				
Pos	0	3.62	4.62	E1	
output		engine			
sun speed	carr. speed	ring		sun speed	output
RPM	12525	3200	624	RPM	
sun torque	carr. torque	ring		sun torque	car. speed
Nm	-29	132	-103	12525	6160
sun power	carr. power	ring		sun torque	car. torque
kW	-37.5	44.2	-6.8	6160	3200
Input EP1					
E1					

slid r value
only
3624
ring speed
RPM slide
E1

EP1/2 = epicyclic stages
E1/2 = electric motors

Full power + 10 kW electric power from external source

highest electric motor power = 16.8 kW (motoring)
10 kW electric power flow from external source

Mechanical and electrical losses are not calculated in this spreadsheet

Fig 4 Sheet 9

**Electric Power Split Transmission
Spread Sheet Model, 74 kW engine at 3200 RPM - 10 kW electric to external source**

	Ro	EP1	EP2
Pos	-3.62	0	-2.15
output	3.62	4.62	3.15
sun speed	engine	ring	engine
RPM	3200	624	3200
sun torque	carr.torque	ring	ring
Nm	153	-120	12525
sun power	carr. power	ring	ring
kW	51.3	-7.8	12525
	43.5	41.3	3200
E1	Input EP1	E1	Output EP2 part engine

slider value
only
3624
ring speed
RPM slide
E1

EP1/2 = epicyclic stages
E1/2 = electric motors

Full power - 10 kW electric power to external source

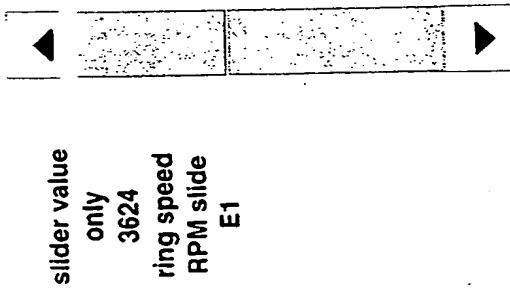
Highest electric motor power = 7.8 kW (generating)
External electric power flow to external source = 10 kW

Mechanical and electrical losses are not calculated in this spreadsheet

Fig 4 Sheet 10

Electric Power Split Transmission
Spread Sheet Model, 10 kW engine braking 3200 RPM

	Ro	EP1	EP2
Ro	-3.62	0	3.15
Pos	0	3.62	4.62
output	engine	E1	
sun speed	carr.speed	ring	
RPM	12525	3200	624
sun torque	carr.torque	ring	
Nm	4	-19	15
sun power	carr. power	ring	
kW	5.5	-6.5	1.0
	E1	Input EP1	E2



slider value
only
3624
ring speed
RPM slide
E1

EP1/2 = epicyclic stages
E1/2 = electric motors

10 kW engine braking

internal electric power flow = 1 kW
no external electric power flow

Mechanical and electrical losses are not calculated in this spreadsheet

Fig 4 Sheet 11

Electric Power Split Transmission Spread Sheet Model, 10 kW electric braking engine at 2000 RPM					
	Ro	Pos	E1	EP2	
Ro	-3.62	EP1	4.62	-2.15	3.15
Pos	0	3.62		2.15	
output	engine			output	
sun speed	carr.speed	ring	sun speed	carr.speed	ring
RPM	2000	-1206	RPM	13606	2000
sun torque	carr.torque	ring	sun torque	carr.torque	ring
Nm	11	-9	Nm	-5	-11
sun power	carr. power	ring	sun power	carr. power	ring
kW	2.4	1.1	kW	-7.6	-2.4
		E1	Input EP1	E1	Output EP2 part engine

▲ ▼

slider value
only
1794

ring speed
RPM slide
E1

EP1/2 = epicyclic stages
E1/2 = electric motors

10 kW electric brake power to external source (regenerative or dump resistor)

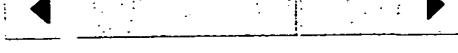
internal electric power flow = 1.1 kW
10 kW external electric power flow

Mechanical and electrical losses are not calculated in this spreadsheet

Fig 4 Sheet 12

Spread Sheet Model 74 kW at 3200 engine input

f rmula sheet		EP1	=B3+1	E1	Ro Pos 0	-2.15 0	EP2	=G3	E2	engine
Pos 0		output	engine	ring	sun speed	sun speed	output	ring		
sun speed		carr.speed	=E7	=E7	RPM	=B7	carr.speed	=C7		
RPM =D7*B3-C7*(B3-1)		carr.torque	=L7	=-3000+B17	sun torque	=-G7/(G3-1)+I7*G3/(G3-1)	carr.torque	=G7		
sun torque		carr.torque	=L9-I9	=-E9*B3	Nm	=H9/(G3-1)	carr.torque	=G9+B9		
Nm =C9/(B3-1)		carr. power	=C7*C9/9550	=D7*D9/9550 =E7*E9/9550	kW	=G7*G9/9550 =-L11	carr. power	=G3*G9		
sun power		Input EP1	E1	E2	E1	=17*I9/9550	ring	=G9+B9		
kW =B7*B9/9550						=I7*J9/9550	ring	=G9+B9		
							part engine	net el.		
								=E11+J11 74		



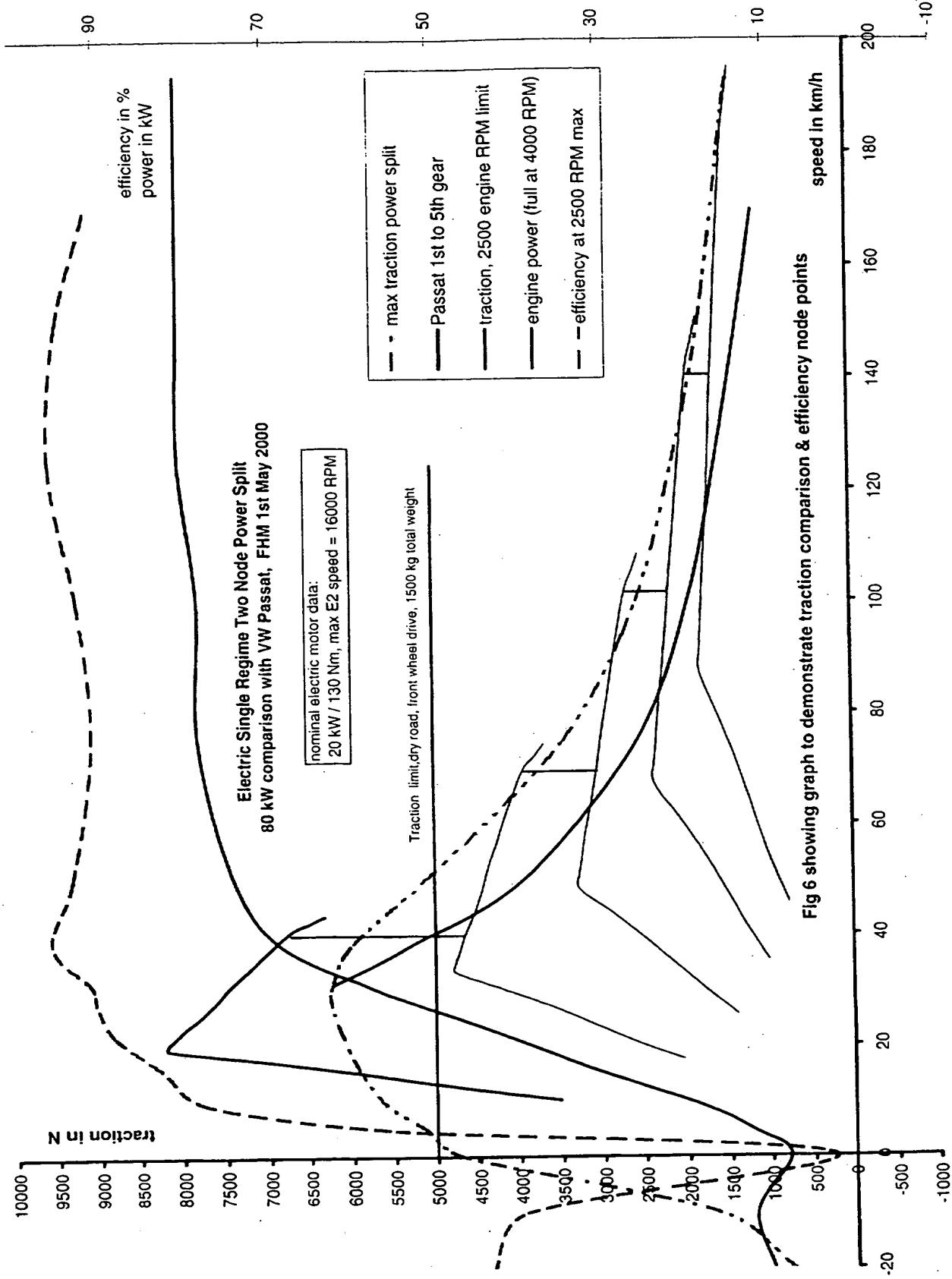
slider value
only
6306
ring speed
RPM slide
E1

Refer to Fig 4 Sheets 1-12

losses are not calculated
on this spreadsheet

**Electric Power Split
Transmission**

Fig 5



PATENTS ACT 1977

A10087GB-JNL/jm

Title: Single Regime Power Split Transmission

Description of Invention

This invention relates to a transmission in or for an automotive vehicle with at least two wheels and of up to approximately 5 tonnes gross weight. Such a transmission is referred to hereinafter as being of the kind specified.

An object of the invention is to provide a new and improved transmission of the kind specified.

According to the invention we provide a transmission of the kind specified comprising a first epicyclic train having a first carrier member, which carries at least one first planet member which is in driving engagement with a first annulus member and with a first sun wheel member and a second epicyclic train comprising a second carrier member, which carries at least one second planet member which is in driving engagement with a second annulus member and with a second sun wheel member wherein the first carrier member is connected to the second annulus member and the first and second sun wheel members being connected together, the first annulus is connected to ground through a first electric motor and the second sun wheel is connected to ground through a second electric motor, one of said members of the first train provides an input to said transmission and one of said members of the second train provides an output of said transmission and there being control means to permit the speed of said motors to be varied to vary the output speed of the transmission.

The first carrier of the first train may provide an input of the said transmission.

The second carrier of the second train may provide an output of said transmission.

The output of the transmission may be connected to the wheels of a vehicle.

The output of the transmission may provide an input to at least one other transmission.

The output of the other transmission or of at least one of the other transmissions may be connected to the wheels of a vehicle.

The output of the transmission or of the other transmission or of at least one of the other transmissions may be connected to the wheels of a vehicle via a clutch means and/or a differential means.

The first motor may comprise a rotor connected to the first annulus member and a stator connected to ground.

The first annulus member may be mounted to rotate fixedly with the rotor of the first motor.

The second motor may comprise a rotor connected to the second sun gear member.

The first sun member and the second sun member may be fixed to rotate with a shaft and the rotor of the second motor may also be adapted to rotate with said shaft.

The first sun member, second sun member and the rotor of the second motor may be longitudinally disposed on said shaft in said order.

Bearing means may be provided between the first carrier member and the first annulus member.

Alternatively, the first planet members and the first annulus member may be mutually supported by virtue of said interengagement therebetween.

All the interengaging members may comprise gear wheels.

Further alternatively, the first planetary members may comprise taper rollers in frictional engagement with said first annulus member and said first sun wheel member.

Biasing means may be provided to bias said planetary members into said frictional engagement and reaction means may be provided for said first annulus member and said first sun wheel member.

Each electric motor may be a switched reluctance motor.

The transmission may be a power split transmission in which means are provided to supply electrical power to one of said motors from the other of said motors.

As a result the transmission does not require any external electrical power supply.

The transmission may be provided with an electrical energy storage means in which electrical power generated by either of said motors is stored.

For example, when the transmission is operated at a relatively slow speed and/or the vehicle is braking an amount of electrical power is generated which is not required by either motor and this is stored in the energy storage means.

Power may be supplied from the energy storage means to at least one of said motors to limit variation in the amount of power supplied to one or other of said motors.

The input of the transmission may be connected to an engine such as an internal combustion engine or an electric motor or indeed any other type of prime mover. Alternatively the input may be connected to an output of any design form of transmission from a prime mover.

The output of the transmission may be connected to the wheels of a vehicle but may be connected into another transmission of any kind including, for example, another power split transmission. Any vehicle within which the transmission is provided may be provided with a plurality of transmissions according to the present invention.

Three embodiments of the invention will now be described by way of example with reference to the accompanying drawings wherein:-

Figure 1 is a diagrammatic representation of a first transmission embodying the invention,

Figure 2 is a diagrammatic representation of a second transmission embodying the invention,

Figure 3 is a diagrammatic representation of a third embodiment of the invention,

Figure 4 comprises twelve tables setting out details of the transmission described herein when connected to a prime mover comprising a 74 kilowatt internal combustion engine operating at 3200 rpm with the transmission set at the twelve different settings referred to in each sheet,

Figure 5 is a spreadsheet setting out how the figures shown in Sheets 1-12 of Figure 4 have been calculated, and

Figure 6 is a graphical illustration in which traction and efficiency are plotted against speed.

Referring now to Figure 1, a transmission is indicated generally at 10 and comprises a housing 11 which provides a ground.

Fixed to the housing 11 is a stator 12 of a first electric motor 13. In the present example, electric motor 13 is of the "switched reluctance" type. The housing 11 also has fixed thereto a stator 14 of a second electric motor 15 also of the "switched reluctance" type.

The housing 11 also carries, via a suitable bearing means 16a, a shaft 16 which is rotatable relative to the housing 11 and fixedly carries a rotor 17 of the motor 15, a second sun wheel member 18 and a first sun wheel member 19, each of which comprises a gear. In addition a bearing, not shown, is provided between an end part 20 of the shaft 16 and a recess 21 provided in a flywheel 22 of a prime mover. The flywheel 22 also provides a first carrier member having a plurality of shafts 23, three in the present example, on each of which a first planet member 24 is rotatably mounted by bearing means 25.

The planet members 24 comprise gears which are in mesh with an annulus member 26, which also comprise a gear, and thus the first annulus member 26, first planetary member 24 together with the first carrier member 23 and the first sun wheel member 19 provide a first epicyclic, gear, train 27.

The annulus member 26 fixedly carries a rotor 28 of the first electric motor 12. Suitable bearing means 29 are provided between the first annulus member 26 and the first carrier member 23.

The first carrier 23 is also connected to a second annulus member 30 which comprises a gear which is in mesh with the second planet members 31 carried by shafts 32 of a second carrier member 33.

The number of first planet members and second planet members although comprising three, in each case, in the present example may be less or more than this figure and either the same or a different number of planet wheels may be provided in each epicyclic train.

The planet members 31 comprises gears are also in mesh with the second sun, gear, member 18 and so the second annulus member 30, said planet member 31 and second sun wheel member 18 together provide a second epicyclic, gear, train 34.

The second carrier member 33 is provided with a set of gear teeth 35 which mesh with a gear 36 carried on a shaft 37 which is carried in bearings 38 carried by the housing 11.

An oil seal 39 is provided between the flywheel 22 and the housing 11. Similarly an oil seal 39a is provided between the housing 11 and the output shaft 37. The shaft 37 is connected, where desired, by a clutch to, for example, wheels or other item to be driven by the transmission and, if desired, in addition, or alternatively, at least one differential may be connected to the shaft 37.

In use, the flywheel 22 is driven by a prime mover which, for example, may be an internal combustion engine or may be of any other desired type

including for example an electric motor. The flywheel 22 is rotated either at a constant speed by the prime mover or the speed of the prime mover is varied so as to vary the speed of rotation of the flywheel. In either case the power provided to the first electric motor 13 from the second electric motor 15 or vice versa is varied as desired to achieve a desired torque split between the two differentials therefore providing a desired output speed of the shaft 37. The variation in the speed of the motors is preferably achieved by a suitable electronic controller programmed according to the desired output of the transmission.

No external electrical power is required to be supplied since electrical power generated by one of the electric motors by rotation of the rotor of the electric motor relative to the stator may be fed to the other electric motor so as to drive its rotor with the electrical power thus generated.

Referring now to Figure 2, in which the same reference numerals have been used as were used in Figure 1 for corresponding parts. This embodiment is similar to that shown in Figure 1 but differs from that shown in Figure 1 by virtue of the absence of a separate bearing means between the first annular member and the first carrier member 23. In this case the gears are manufactured accurately so that the gears interengage and act as a bearing means. In addition the first rotor 29 is symmetrically disposed relative to the stator 12 so as to avoid any axial loads. In addition, the planet members are equally spaced so that there are no offset loads to upset the balance.

In the embodiment shown in Figure 3, again the same reference numerals have been used to refer to corresponding parts as were used in Figure 1 but in this case instead of the first annulus member 26 being provided with teeth which engage with the teeth of the first planetary wheel members 24, which are themselves engaged with the first sun gear 19, the first annulus member, first planetary members and first sun wheel are formed as tapered rollers, which are axially forced into engagement to provide a frictional drive.

For this reason these components are indicated in Figure 3 by the same reference numbers as used in Figures 1 and 2 with the addition of a prime sign.

The required axial load is achieved by providing the Belleville washers indicated at 40 in Figure 3 which serve to urge the first planetary wheel members 24' to the right in Figure 3 and so cause frictional engagement between the first planetary wheel members 24' and the first annulus member 26' and the first sun wheel member 19' respectively. To accommodate the thrust thus provided by the Belleville washers 40, thrust bearing means 41, 42 are provided. In addition, because of built in non-symmetrical disposition of the stator and rotor 26, 28 on rotation additional magnetic loads which are torque dependent will be created which are supported by the thrust bearing means 43.

It should be noted that for starting the engine it is not necessary to disengage any clutches with which the engine may be provided since the electric motors can keep the vehicle stationary during the starting procedure. If a clutch is provided and if it is disengaged in an emergency then the electric motors can synchronise the relevant clutch halves for easy engagement.

In any of the embodiments described hereinbefore if desired energy storage means, for example a suitable battery, may be connected to at least one and preferably to both of the motors. As a result when the transmission is operated at a relatively slow speed and/or the vehicle is braking an amount of electrical power is generated and this is fed to and stored in the energy storage means.

Power may be supplied from the energy storage means to at least one of the motors to limit variation in the amount of power supplied to the other of said motors.

If desired electrical power may be supplied to other external means such as regenerative or dump resistor to assist in braking of the engine for example as shown in Sheet 12 of Figure 4.

It is important to maintain the power requirements of the electrical motors to a minimum to reduce cost and to increase transmission efficiency particularly as electrical control of motors can be expensive for high powers and the efficiency of motors and generators combined is not greater than for example 80% whereas mechanical efficiency can be as high as 97% for example.

The present invention provides a power shaft transmission which circulates relatively little electrical power, especially if the engine speed is always readjusted by the vehicle controller to run the transmission close to one of the electrical power node points. These node points occur, when one of the motors is at a standstill and therefore cannot generate nor absorb any power. This is the condition shown in Sheets 3 and 4 of Figure 4.

It will be clear to a person of skill in the art that for each different vehicle and engine combination the ratios of the transmission have to be adjusted to make the node points most effective.

In the present specification "comprise" means "includes or consists of" and "comprising" means "including or consisting of".

The features disclosed in the foregoing description, or the following claims, or the accompanying drawings, expressed in their specific forms or in terms of a means for performing the disclosed function, or a method or process for attaining the disclosed result, as appropriate, may, separately, or in any combination of such features, be utilised for realising the invention in diverse forms thereof.

CLAIMS

1. A transmission of the kind specified comprising a first epicyclic train having a first carrier member, which carries at least one first planet member which is in driving engagement with a first annulus member and with a first sun wheel member and a second epicyclic train comprising a second carrier member, which carries at least one second planet member which is in driving engagement with a second annulus member and with a second sun wheel member wherein the first carrier member is connected to the second annulus member and the first and second sun wheel members are connected together, the first annulus is connected to ground through a first electric motor and the second sun wheel is connected to ground through a second electric motor, one of said members of the first train provides an input to said transmission and one of said members of the second train provides an output of said transmission and there being control means to permit the speed of said motors to be varied to vary the output speed of the transmission.
2. A transmission according to Claim 1 wherein the first carrier of the first train provides an input of the said transmission.
3. A transmission according to Claim 1 or Claim 2 wherein the second carrier of the second train provides an output of said transmission.
4. A transmission according to any one of the preceding claims wherein the output of the transmission is connected to the wheels of a vehicle.
5. A transmission according to any one of Claims 1 to 3 wherein the output of the transmission provides an input to at least one other transmission.

6. A transmission according to Claim 5 wherein the output of the other transmission or of at least one of the other transmissions is connected to wheels of a vehicle.
7. A transmission according to any one of Claims 4 to 6 wherein the output of the transmission or said other transmission or at least one of the other transmisisons is connected to the wheels of a vehicle via a clutch means and/or a differential means.
8. A transmission according to any one of the preceding claims wherein the first motor comprises a rotor connected to the first annulus member and a stator connected to ground.
9. A transmission according to Claim 8 wherein the first annulus member is mounted to rotate fixedly with the rotor of the first motor.
10. A transmission according to any one of the preceding claims wherein the second motor comprises a rotor connected to the second sun gear member.
11. A transmission according to Claim 10 wherein the first sun member and the second sun member are fixed to rotate with a shaft and the rotor of the second motor is also be adapted to rotate with said shaft.
12. A transmission according to Claim 11 wherein the first sun member, second sun member and the rotor of the second motor are longitudinally disposed on said shaft in said order.

13. A transmission according to any one of the preceding claims wherein bearing means are provided between the first carrier member and the first annulus member.
14. A transmission according to any one of Claims 1 to 12 wherein the first planet members and the first annulus member are mutually supported by virtue of said interengagement therebetween.
15. A transmission according to Claim 14 wherein all the interengaging members comprise gear wheels.
16. A transmission according to Claim 14 wherein the first planetary members comprise taper rollers in frictional engagement with said first annulus member and said first sun wheel member.
17. A transmission according to Claim 16 wherein biasing means are provided to bias said planetary members into said frictional engagement and reaction means may be provided for said first annulus member and said first sun wheel member.
18. A transmission according to any one of the preceding claims wherein each electric motor is a switched reluctance motor.
19. A transmission according to any one of the preceding claims wherein the transmission is a power split transmission in which means are provided to supply electrical power to one of said motors from the other of said motors.

20. A transmission according to any one of the preceding claims wherein the transmission is provided with an electrical energy storage means in which electrical power generated by either of said motors is stored.
21. A transmission according to Claim 20 wherein the power is supplied from the energy store to at least one of said motors.
22. A transmission substantially as hereinbefore described with reference to Figure 1 or Figure 2 or Figure 3 and Figures 4 to 6 of the accompanying drawings.
23. A transmission according to any one of the preceding claims wherein the transmission is connected to another transmission.
24. A transmission according to Claim 22 wherein said other transmission is of the same kind as the transmission claimed in Claims 1 to 22 is of a different kind.
25. Any novel feature or novel combination of features described herein and/or in the accompanying drawings.



Application No: GB 0013727.3
Claims searched: 1 to 24

Examiner: Mike McKinney
Date of search: 21 September 2001

Patents Act 1977
Search Report under Section 17

Databases searched:

UK Patent Office collections, including GB, EP, WO & US patent specifications, in:
UK CI (Ed.S): F2D (DEC).
Int CI (Ed.7): F16H 3/72.
Other: ONLINE: WPI; EPODOC; JAPIO.

Documents considered to be relevant:

Category	Identity of document and relevant passage		Relevant to claims
A	US 5730676	(SCHMIDT)	
A	US 5603671	(SCHMIDT)	
A	US 5577973	(SCHMIDT)	
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